

Forward and Inverse EEG Source Modeling

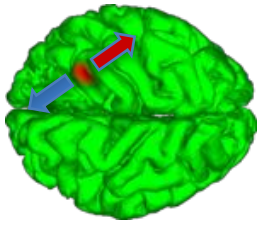


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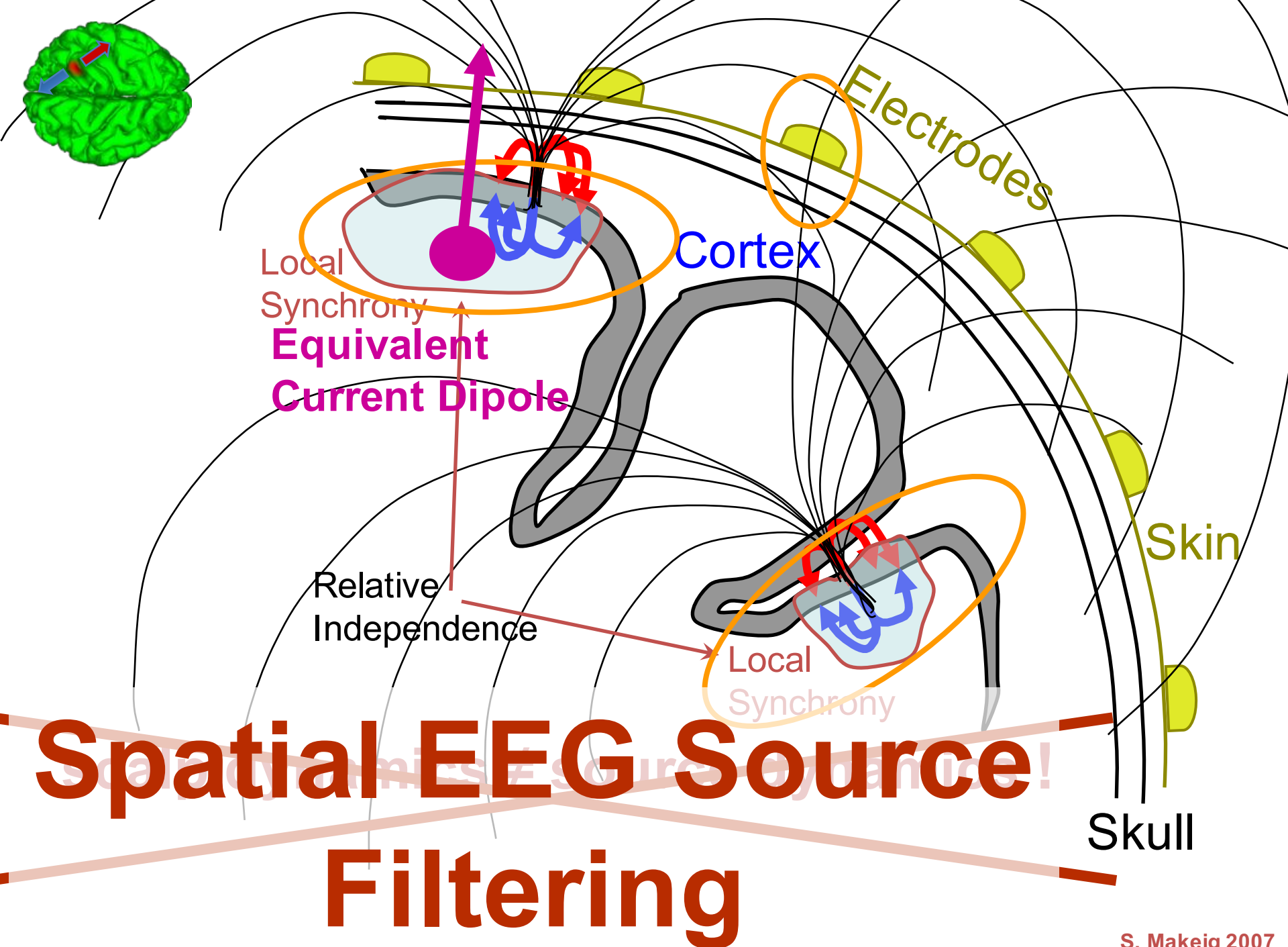
January, 2017



Motivation

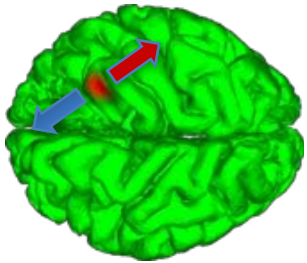
- Why perform ICA?
- Why fit dipoles or distribution source models?
- Why measure EEG?!

- To obtain information about brain processes...
 - Time course of activities that produce the EEG signals
 - Locations of the activities that produce the EEG signals



EEG source modeling

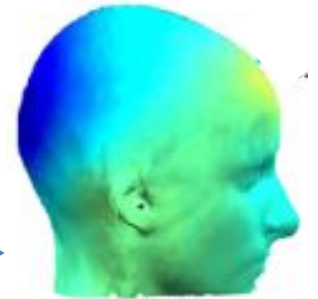
Source
Space



Forward head model

forward problem

Sensor
Space



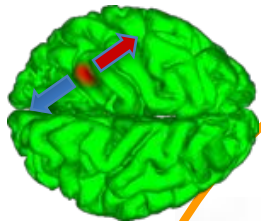
electrical
currents

volume conduction
through body tissues

recorded
potentials

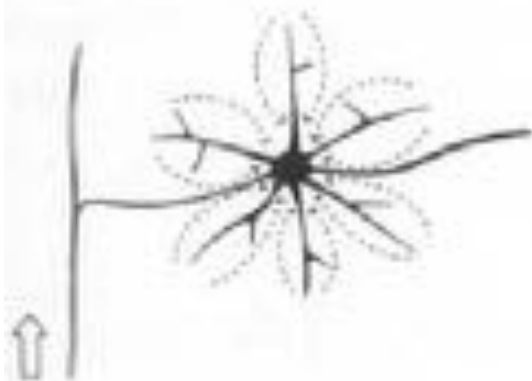
inverse problem

Inverse localization
method

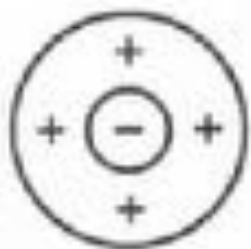


Peri-neuronal currents

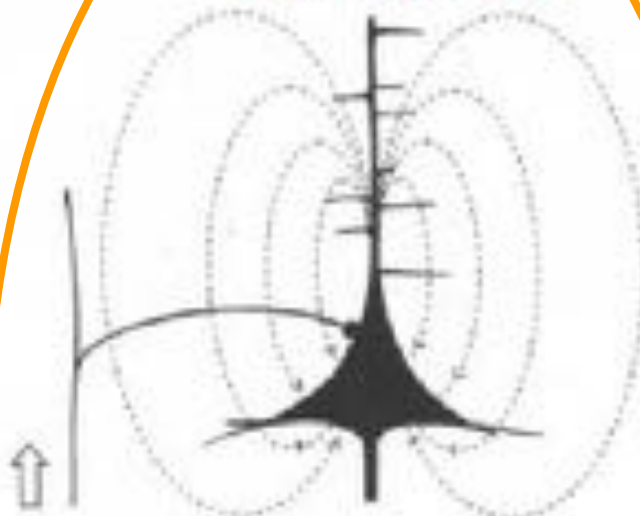
Stellate cell



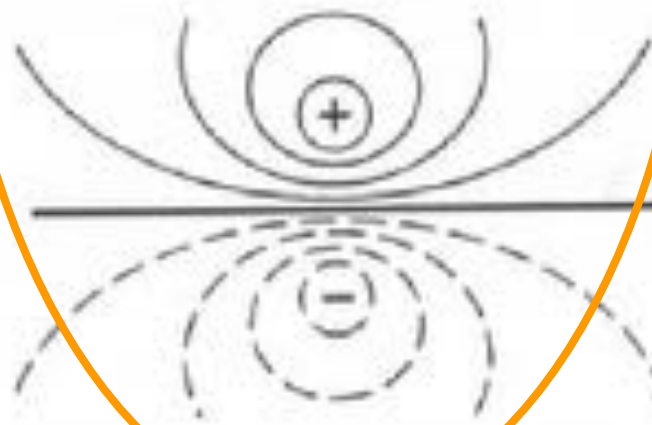
Closed field

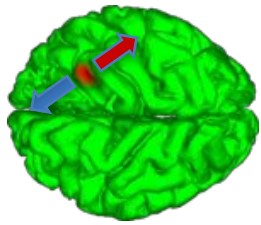


Pyramidal cell



Open field



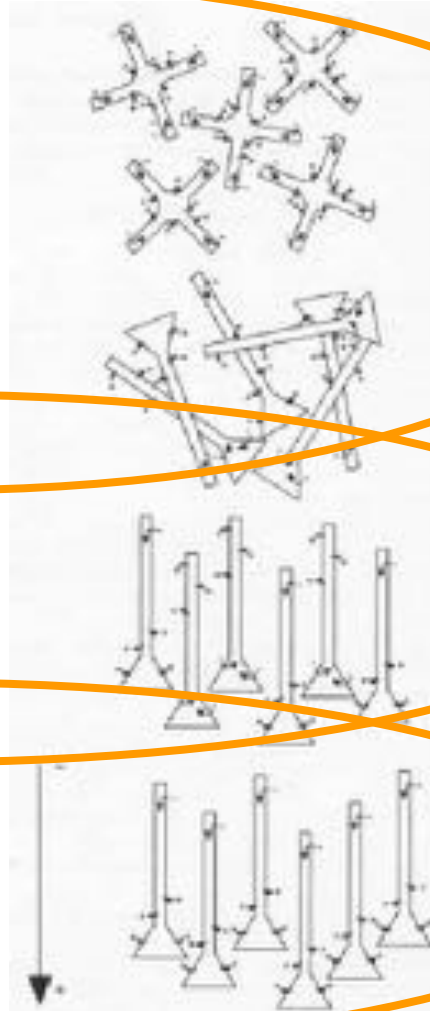


Symmetry, orientation and activation

radially symmetric, i.e.
randomly-oriented

asynchronously activated

synchronously activated
parallel-oriented

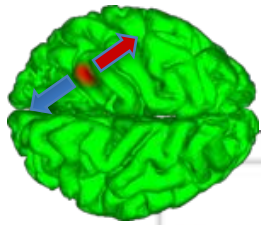


Closed field

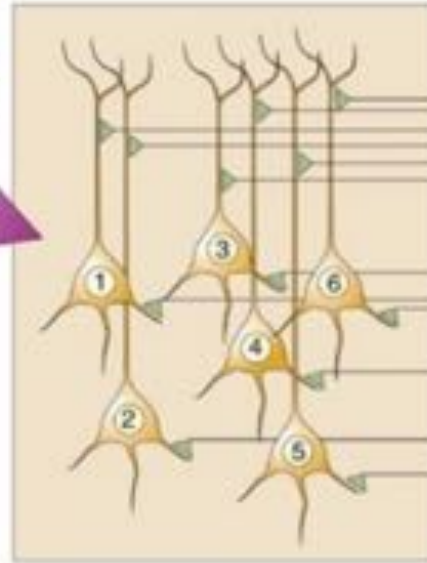
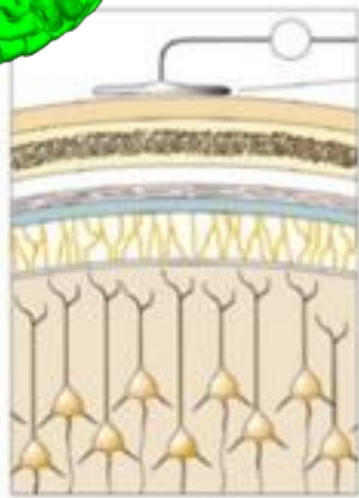
Phase
cancellation

Open field

When recorded at a distance, dipolar field components dominate

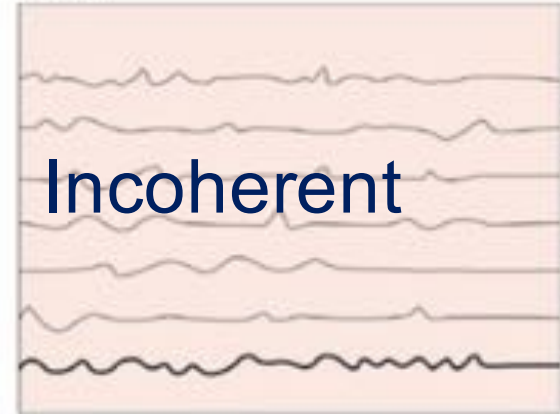


EEG Effective Sources



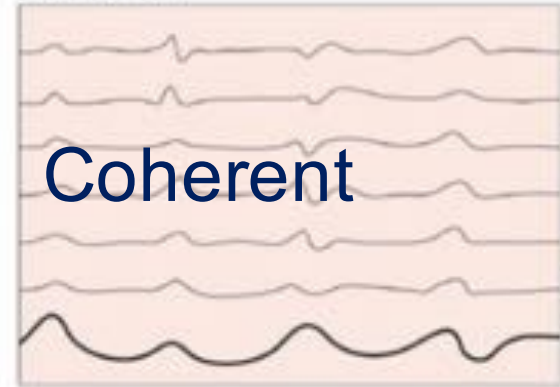
(a)

Irregular



(b)

Synchronized

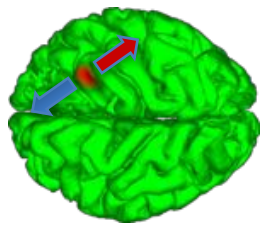


(c)

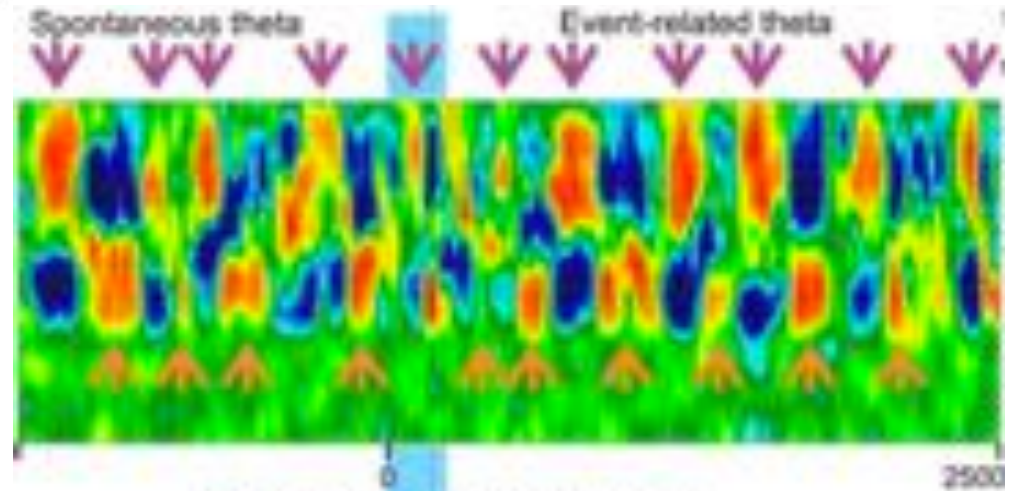
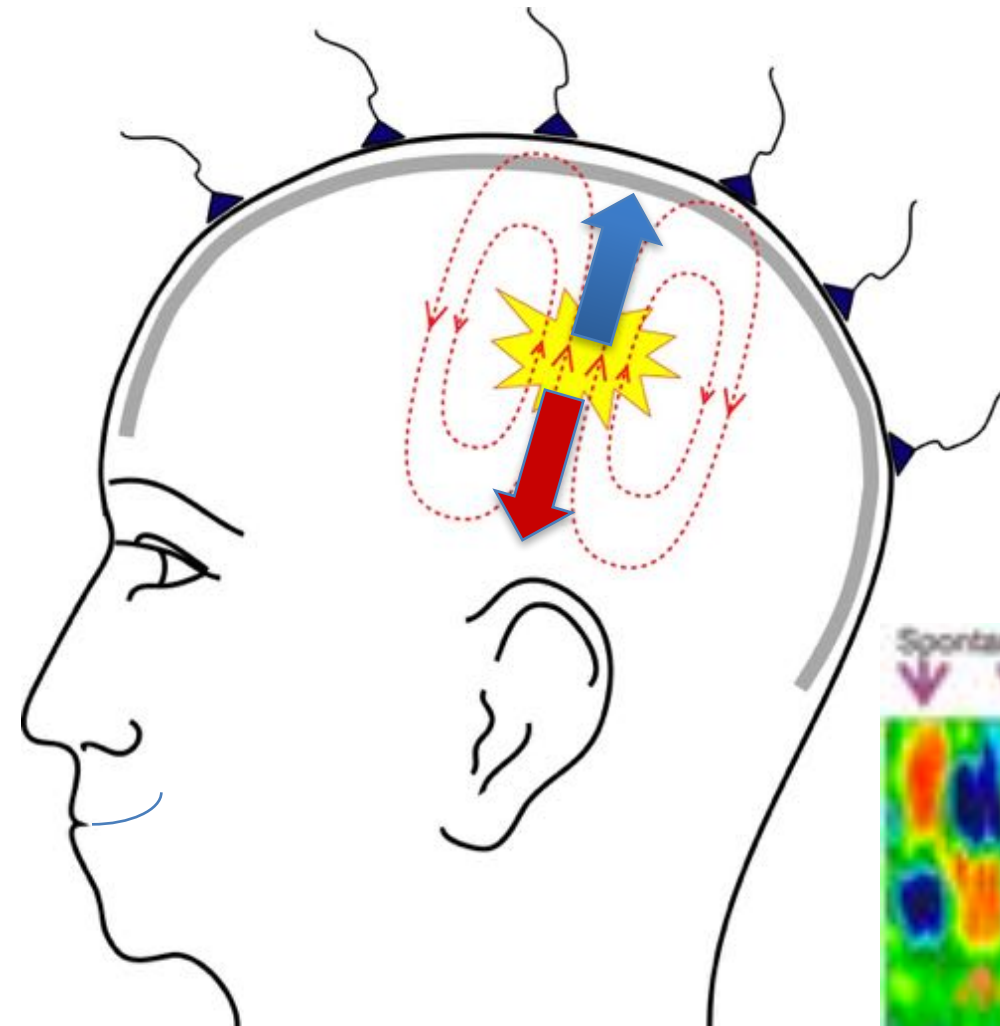
Σ = EEG

Σ EEG

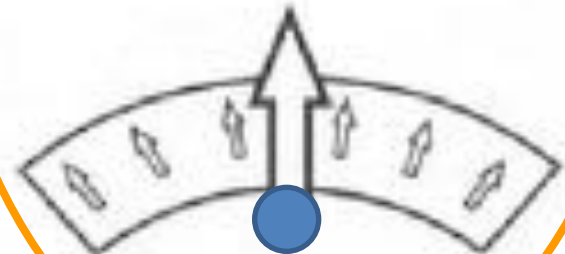
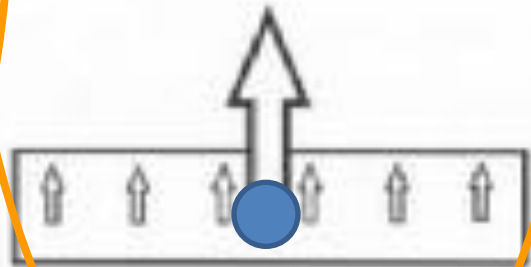
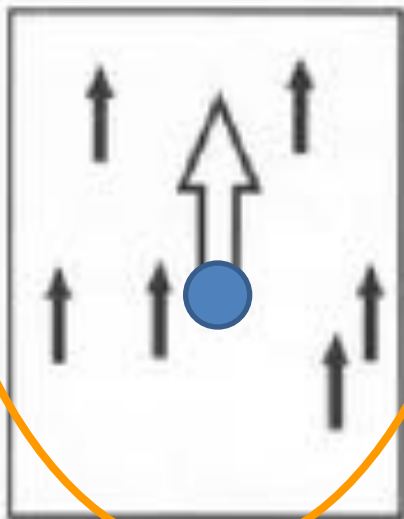
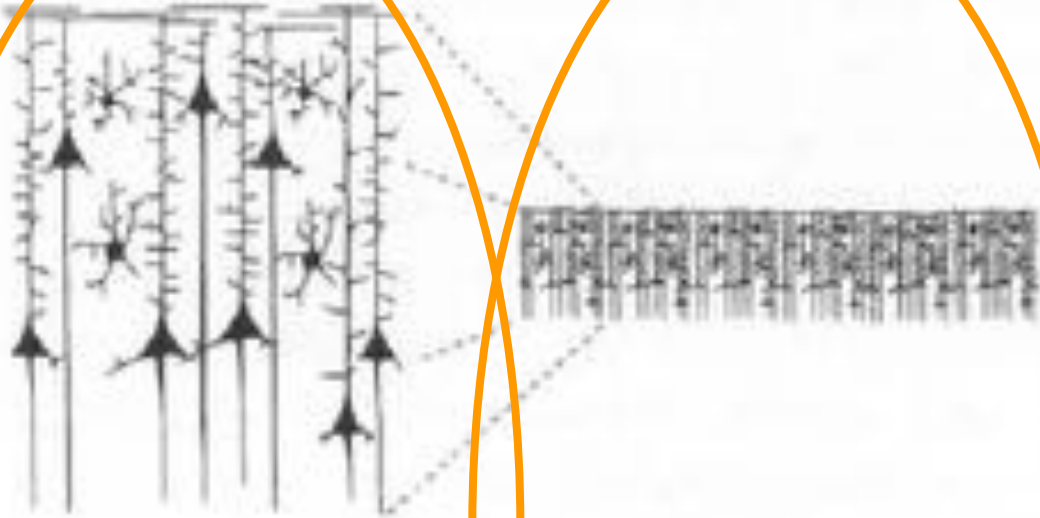
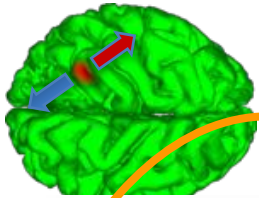
Many neurons need to sum their local field activities to be detectable at EEG electrodes. Synchronized neural activity produces large far field signals.

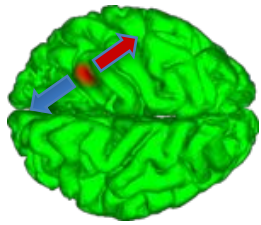


EEG volume conduction of dipolar field patterns → effective sources

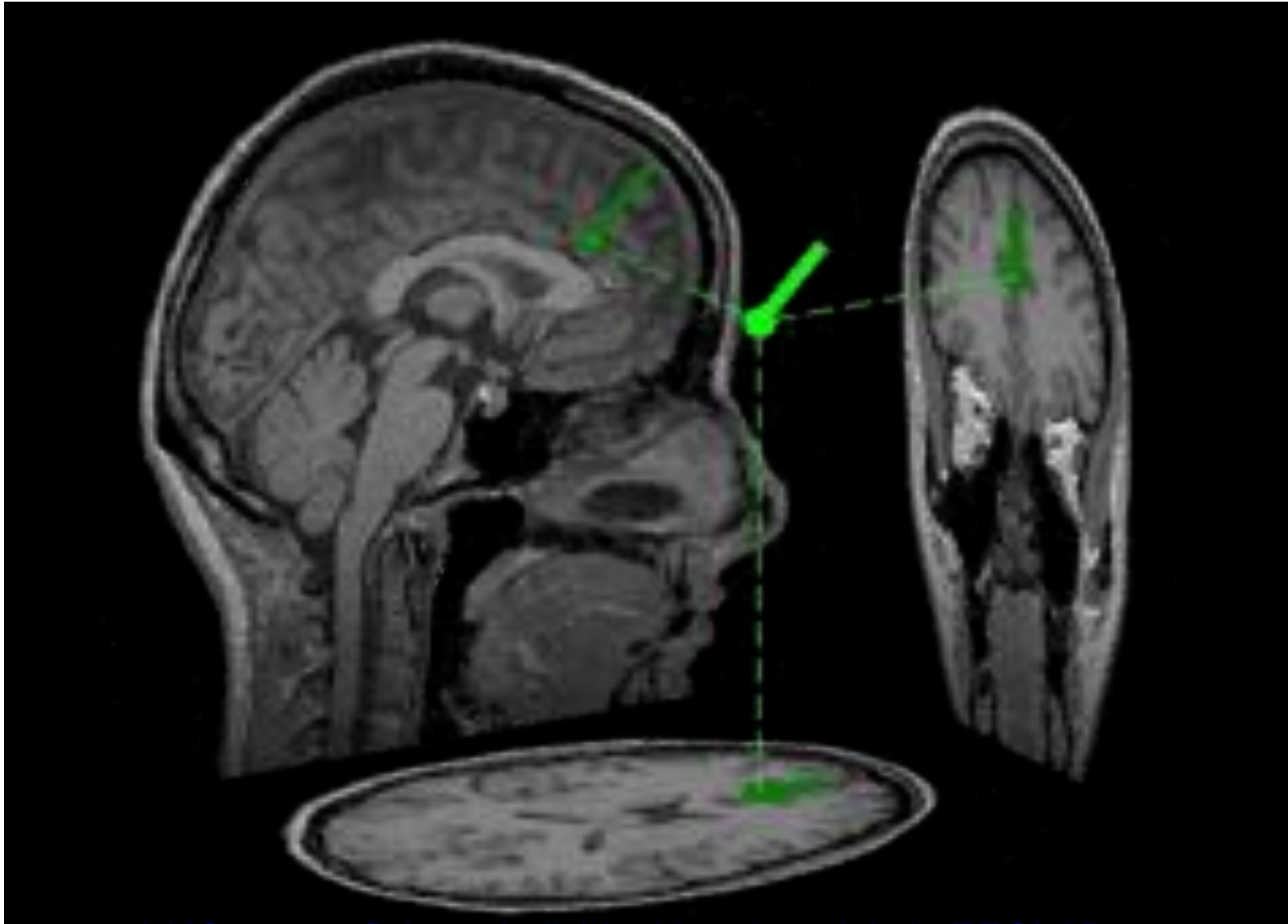


The *equivalent* current dipole





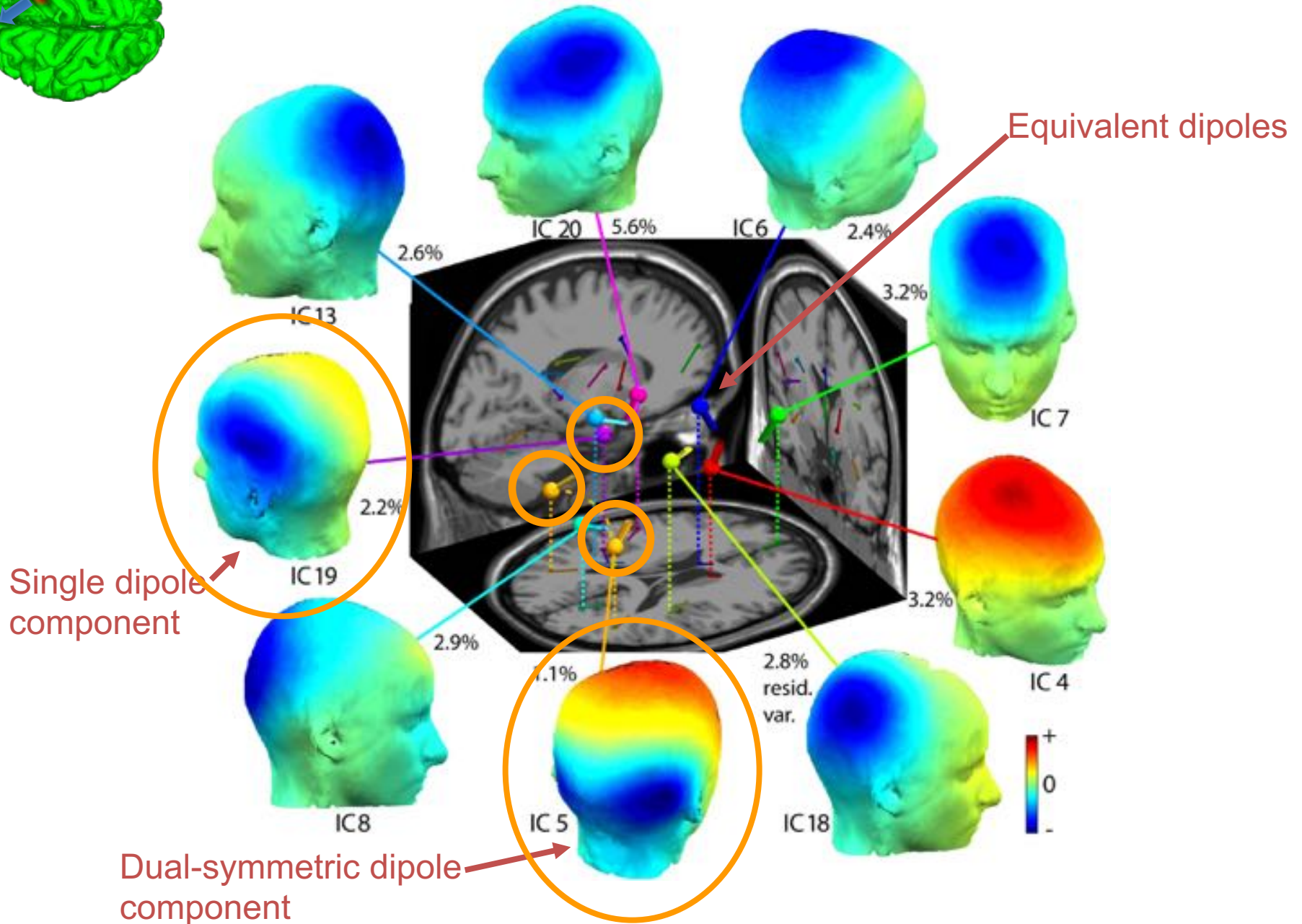
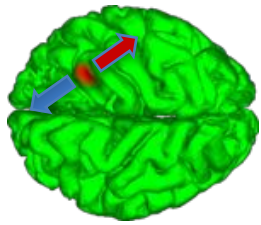
Equivalent current dipole modeling

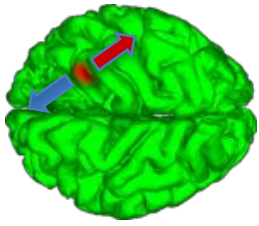


1st IC source fit in an individual head model via EEGLAB

A. Delorme, ~2007

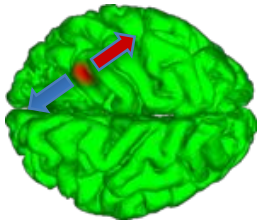
Independent cortical components





Equivalent current dipole modeling

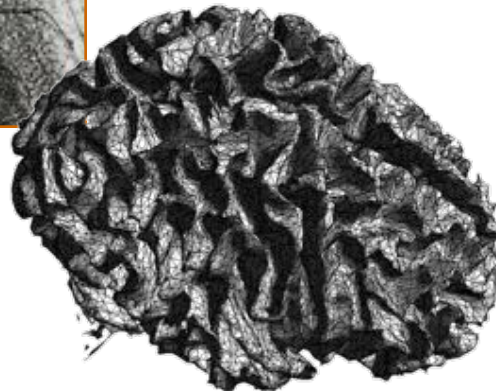
- **Physical/mathematical motivation**
 - Any current distribution can be written as a multipole expansion
 - First term: monopole (must be 0)
 - Second term: dipole
 - Higher order terms: quadrupole, octopole, ...
 - **In far-field recordings, the dipolar term dominates.**
- For convenience + accuracy, therefore
 - **Dipoles** can be used as building blocks in distributed EEG effective source models



The linear forward problem

$$X = LS$$

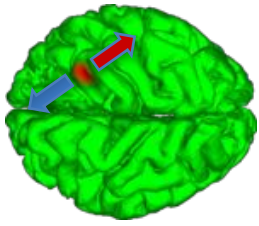
where L is the lead field matrix giving Potential vector contributions X to each scalp electrode for all possible source contributions S (source space)



Anatomical constraint:
Sources are
in the cortex &
perpendicular to it.

Daunizeau, 2009

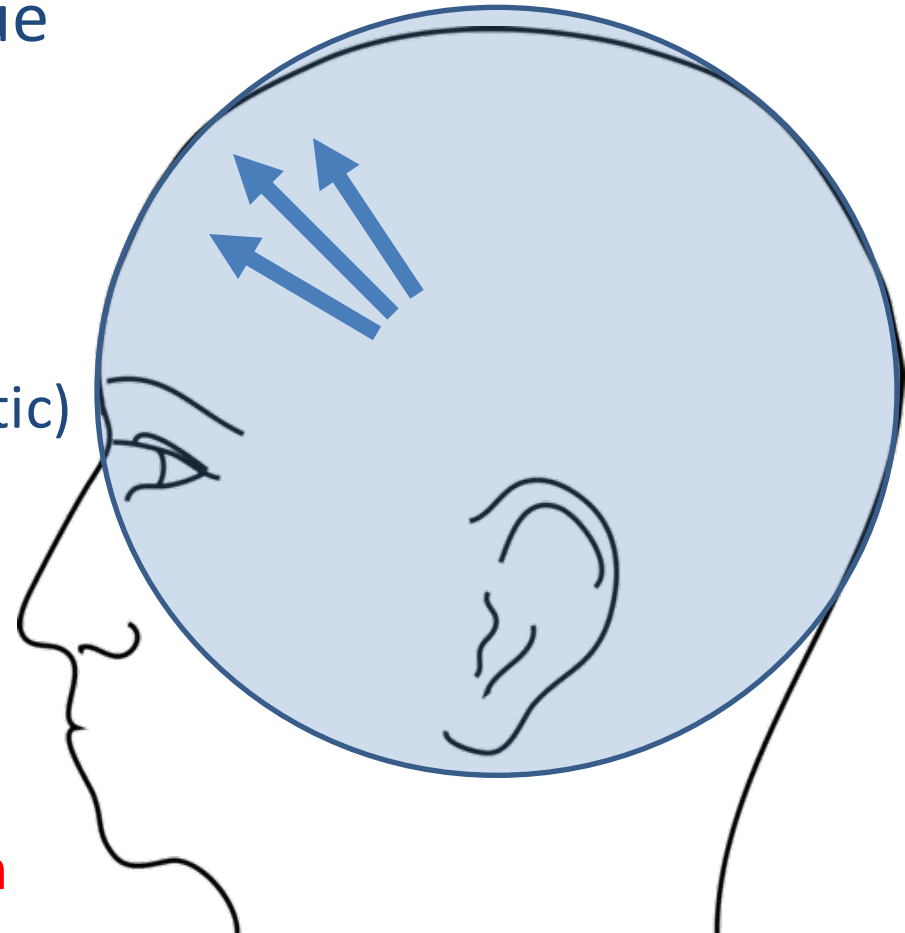


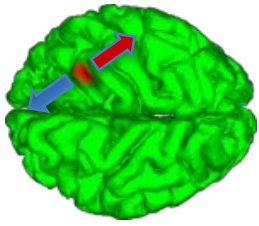


Forward Head Models

- Electrical properties of tissue
 - Conductivity
 - Anisotropy
- Geometrical description
 - Spherical model? (less realistic)
 - Realistically shaped model

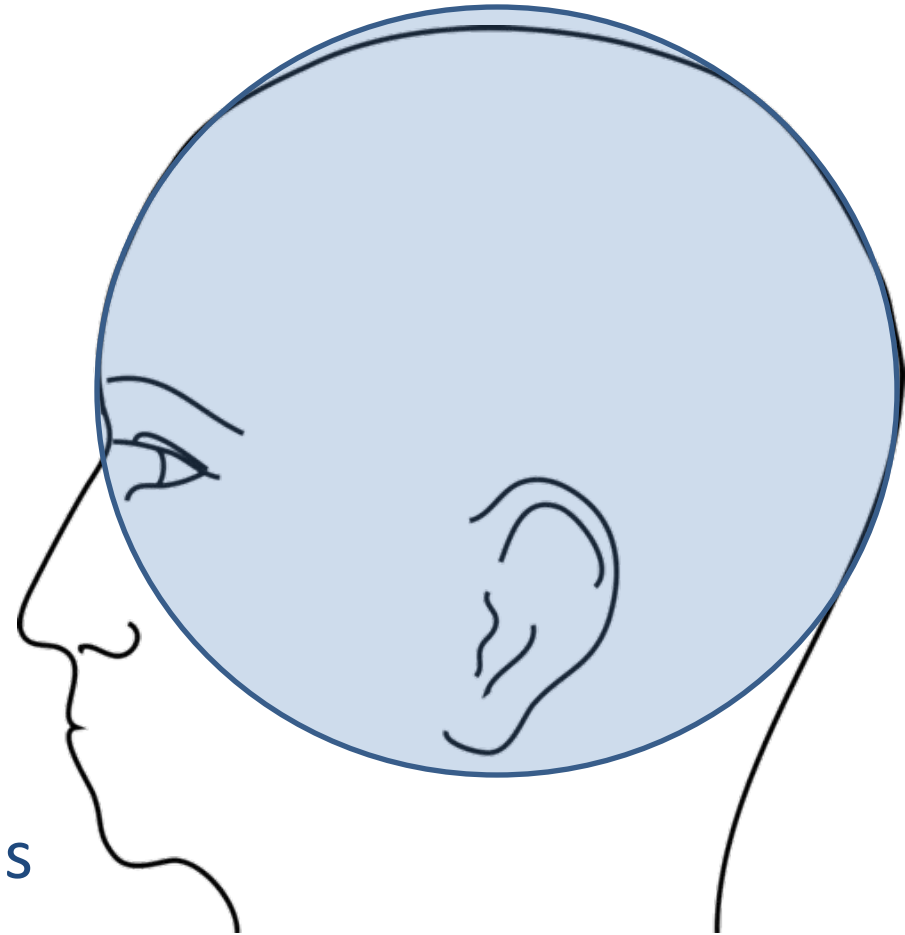
→ A **forward model** describes how the currents flow from all possible points of origin

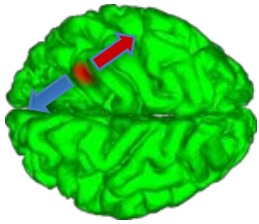




Forward Head Models

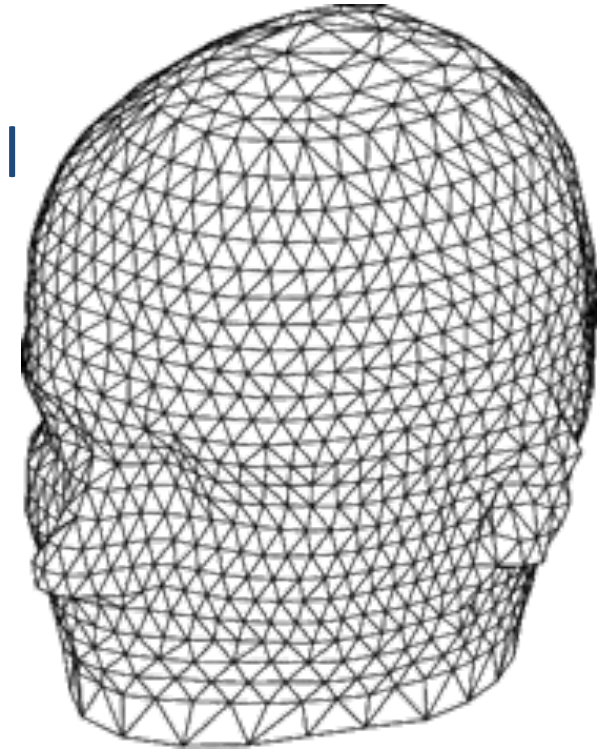
- Advantages of the **spherical** model
 - mathematically accurate
 - reasonably accurate
 - computationally fast
 - easy to use
- Disadvantages of the **spherical** model
 - inaccurate in some regions
 - difficult to align to head



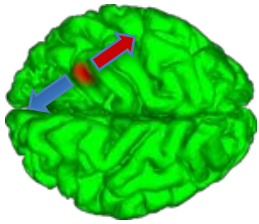


Forward Head Models

- Advantages of a **realistic** head model
 - accurate solution for EEG
- Disadvantages of a **realistic** model
 - more work
 - computationally slower
 - numerically instable?
 - Difficult for inter-individual comparisons

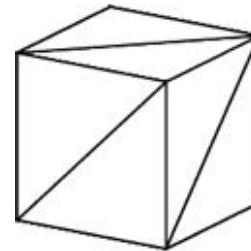
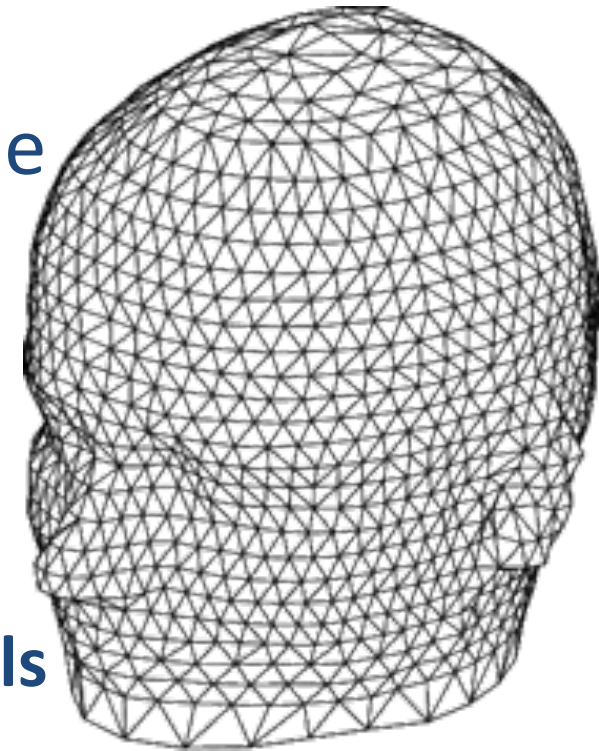


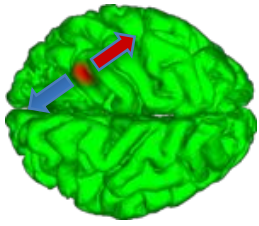
→ The pragmatic (easy, cheap) solution is to use a standard (mean) realistic head model (MNI).



Forward Head Models

- Computational methods for volume conduction problem that allow realistic geometries
 - **Boundary Element Method (BEM) models**
 - **Finite Element Method (FEM) models**
- Geometrical description
 - **Triangles (2-D) \rightarrow BEM**
 - **Tetrahedra (3-D) \rightarrow FEM**



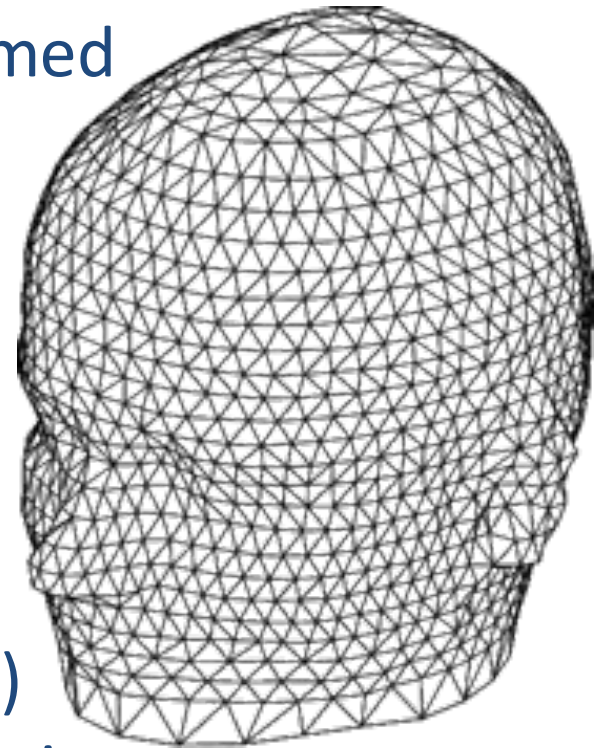


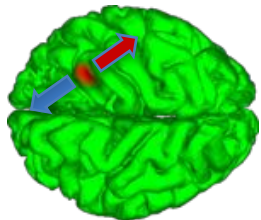
Forward Head Models: BEM

- **Boundary Element Method (BEM)** models
 - description of head geometry by tissue compartments
 - Tissue in each compartment is assumed
 - homogenous
 - isotropic

Important tissue types

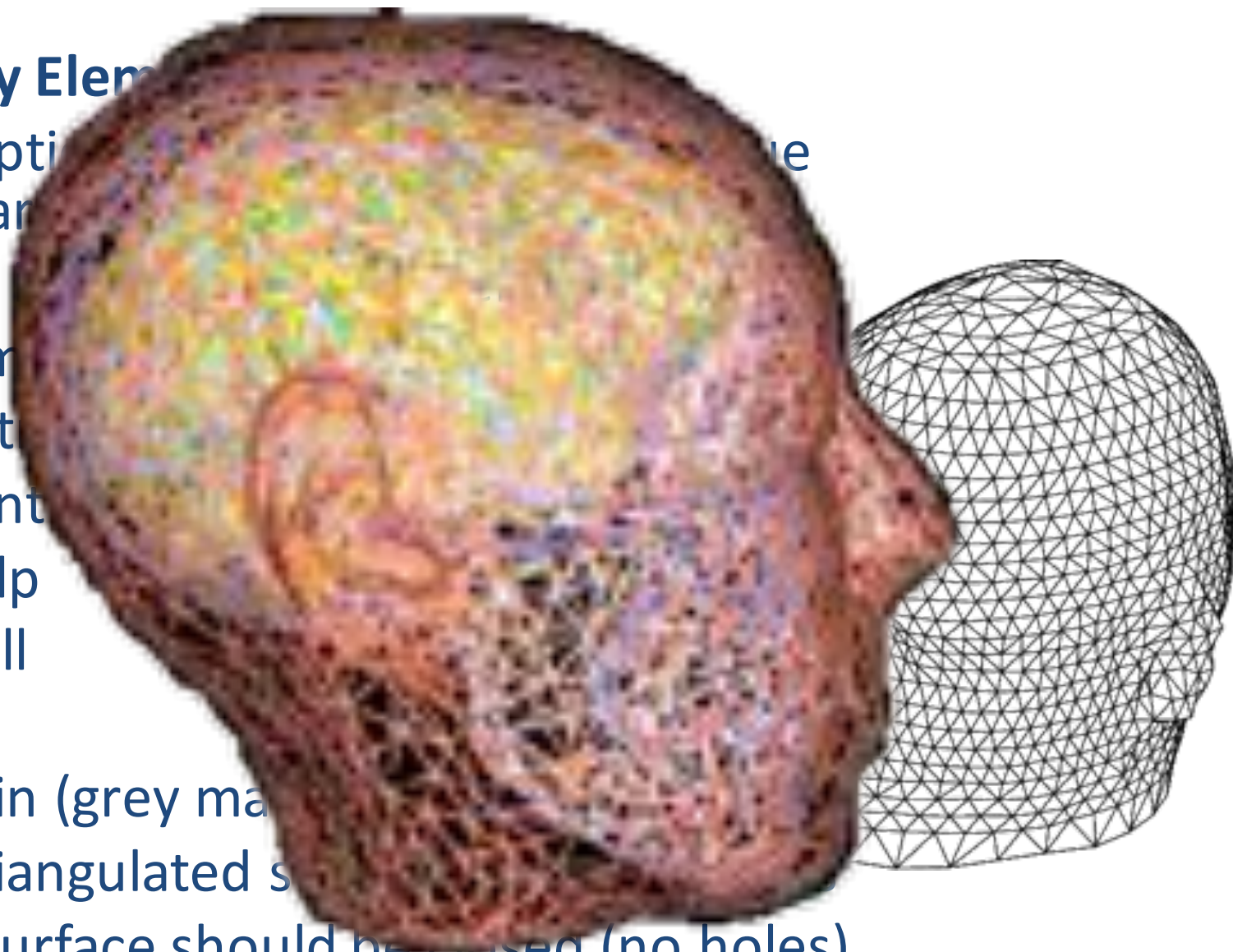
- Scalp
- Skull
- CSF
- Brain (grey matter / white matter)
- Use triangulated surfaces as boundaries
- Each surface should be closed (no holes)

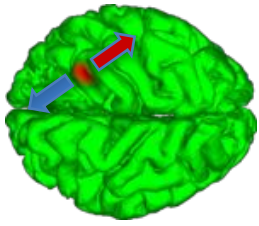




Forward Head Models: BEM

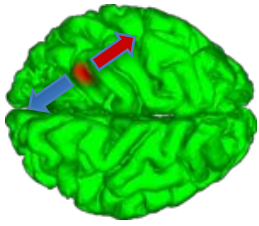
- **Boundary Element Method (BEM)**
 - descriptive of the geometry of the head
 - comparison of different head models
 - Tissue properties
 - homogeneous
 - isotropic
- **Important layers**
 - Scalp
 - Skull
 - CSF
 - Brain (grey matter)
- Use triangulated surfaces
- Each surface should be closed (no holes)





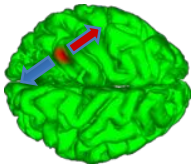
Forward head models: Modeling the skull

- **Potential differences between electrodes** measures summed current flowing through scalp
 - However, only a tiny fraction of *brain source currents* pass through the skull
 - Therefore a forward head model should describe *brain, skull, and scalp tissues* as accurately as possible.



Forward head models: Modeling the skull

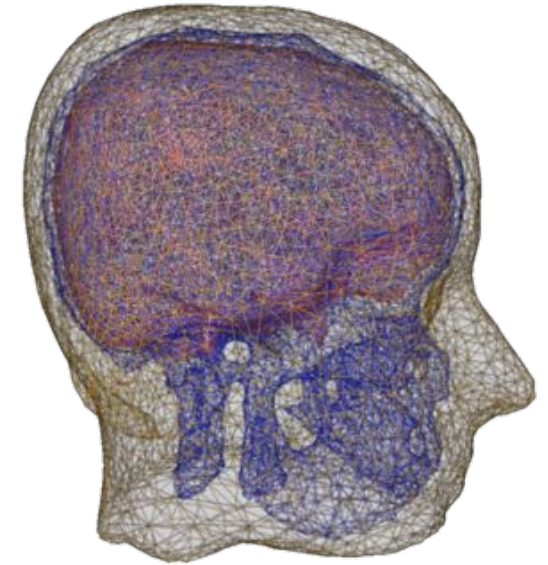
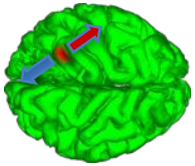
- **Problems with skull modeling**
 - Poorly visible in the anatomic MRI (T2) image
 - Thickness varies regionally
 - Conductivity is not homogeneous
 - Complex geometry at front and base of skull
 - **Skull conductivity** variable & unknown



Volume conductor: FEM

To make a Finite Element Method (FEM) head model:

- **Tessellate the 3-D volume into solid tetrahedra**
 - Contains a large number of 3-D elements
 - Each tetrahedron can have its own conductivity
 - Each tetrahedron can have its own *anisotropy*
(direction-dependent conductivity differences)
- **FEM is the more complete numerical method (> BEM)**
 - But is computationally expensive
 - Note: Accurate conductivities are not known, particularly for skull (and scalp?).



Head Modeling Errors

Electrode & MRI Co-registration errors

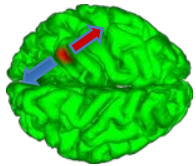
Head Geometry Errors

EXCLUSION of white matter

Two Few electrodes

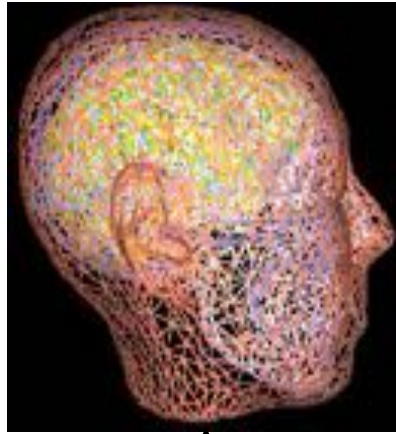
Poor distribution of electrodes

→ mis-estimation of skull conductivity



Electromagnetic source localization using realistic head models (Dipfit, NFT)

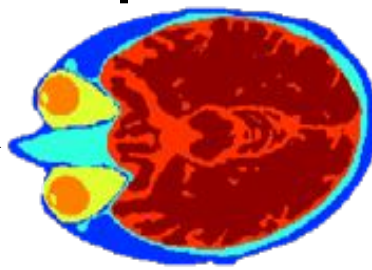
Solve the forward problem using realistic head models (BEM)



Mesh generation

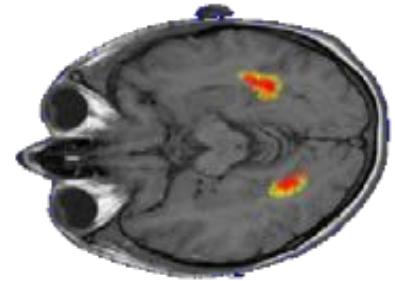


MRI



Segmentation

Simple Map



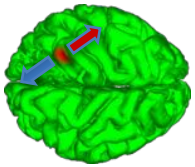
Source Image

Sensor Localization

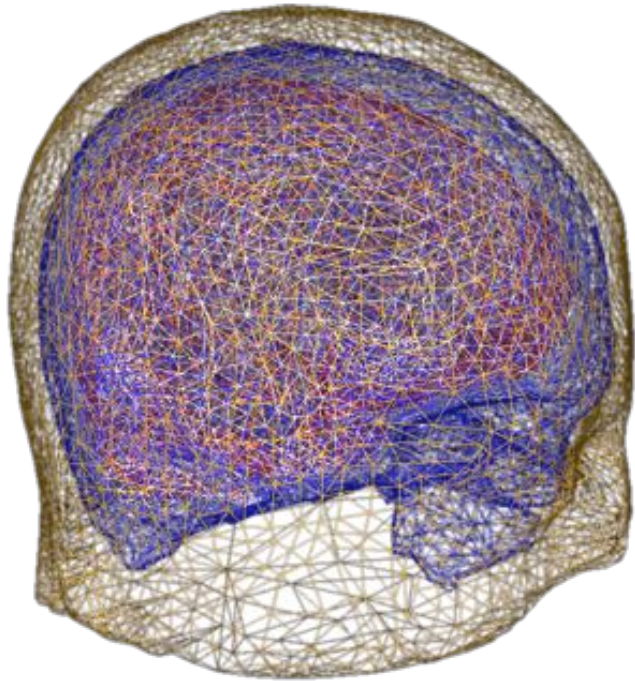
Signal Processing



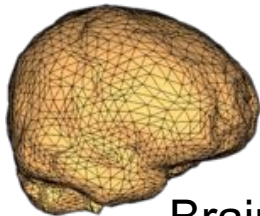
EEG/MEG



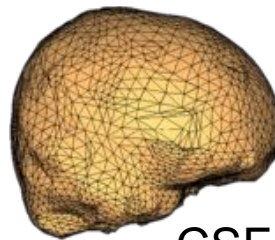
The MNI Head Model



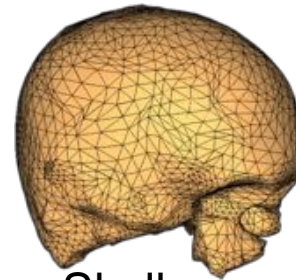
- 4-layer
 - 16856 nodes
 - 33696 elements
- 3-layer
 - 12730 nodes
 - 25448 elements



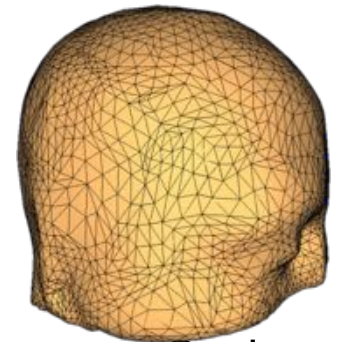
Brain



CSF

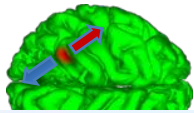


Skull



Scalp

NFT



Subject Folder

Subject Name

Session Name

Head Modeling

From a magnetic Resonance Image

Image Segmentation

Mesh Generation

Source Space Generation

Electrode Co-Registrati...

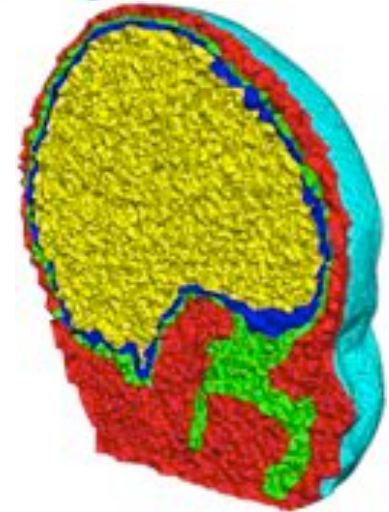
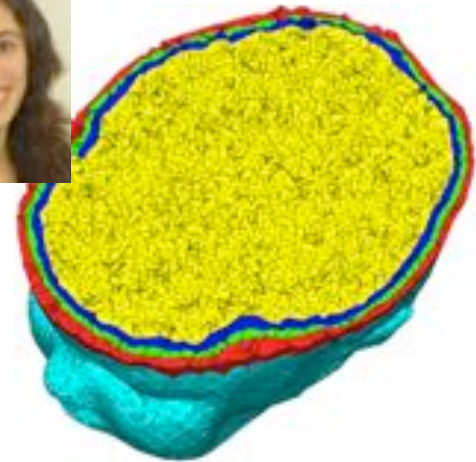
From electrode Position Data

Template Warping

FP Solution with BEM

FP Solution with FEM

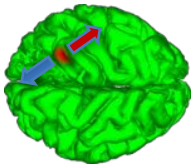
Dipole Fitting



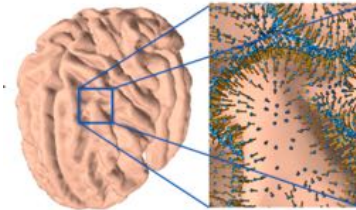
FEM models



BEM models



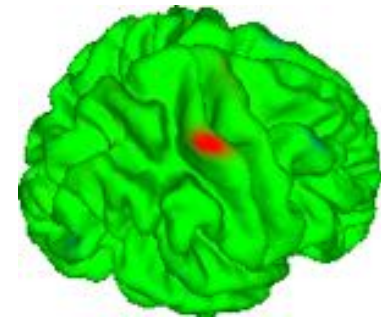
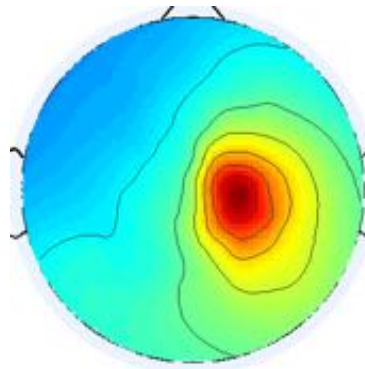
NIST



Source space

Scalp map

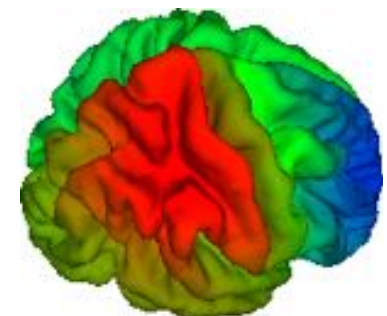
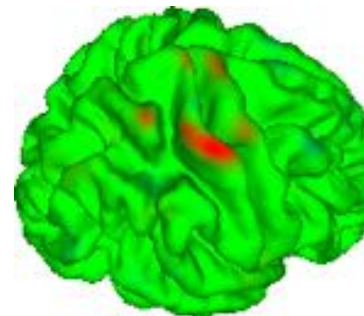
SCS

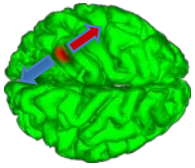


Cheng Cao, 2012

Patch-based SBL

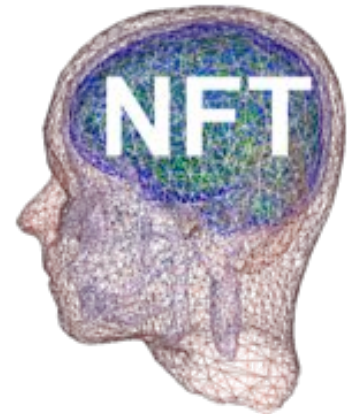
sLORETA

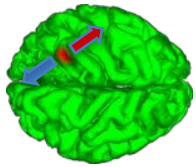




Head Model Generation Summary

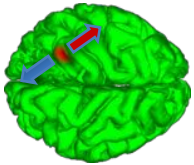
- **Subject-specific Head Model (NFT)**
 - From whole head T1 weighted MR of the subject
 - 4-layer realistic BEM model
- **MNI Template Head model (DIPFIT)**
 - From the MNI head
 - 3-layer and 4-layer template BEM model
- **Warped MNI Template Head Model (NFT)**
 - Warp MNI template to EEG sensors
- **Spherical Head model (no longer in use)**
 - 3-layer concentric spheres
 - Fitted to EEG sensor locations
 - Not accurate





Inverse source localization

- **Single and multiple dipole models**
 - Minimize error between the model and the measured potential/field
- **Distributed dipole models**
 - Seek perfect fit to the measured potential or field
 - Must minimize **some additional source constraint**
 - LORETA assumes a smooth source current distribution
 - Minimum Norm (L2), min. total cortical $|\text{current}|^2$
 - Minimum Current (L1) min. total cortical $|\text{current}|$
 - Note: L2/L1 need some weighting scheme to keep source models from being too broad & superficial.



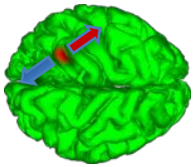
Inverse methods

Spatial filtering approaches

- **Scan whole brain** with single dipole and compute the filter output at every location (using sensor covariance)
 - MUSIC
 - *Beamforming* (e.g. LCMV, SAM, DICS)
- **Perform ICA decomposition** (higher-order statistics) on the continuous data.
 - ICA gives the projections of the sources to the scalp surface → **‘simple’ maps!**

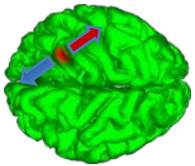
→ ICA solves **‘the first half’** of the inverse problem **‘What?’**

→ ICA gives **‘simple’** source maps, helping to locate **‘Where?’**



Single or multiple dipole models

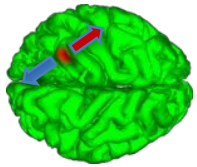
- Manipulate source parameters to **minimize error** between measured and model data
 - The **position** of each source
 - The **orientation** of each source
 - The **strength (magnitude)** of each source
- **Dipole orientation** and **strength** together correspond to the “**dipole moment**,” estimated linearly
- **Dipole position** is estimated non-linearly by source parameter estimation



DIPFIT: Dipole fitting 1. Grid search

1. Coarse fit step

- Define a grid with possible dipole locations
- Compute optimal dipole moment at each location
- Compute value of goal-function (fit to given map)
- Plot value of goal-function on the grid → find best fit.
- Number of evaluations:
 - single dipole, 1 cm grid: ~4,000
 - single dipole, ½ cm grid: ~32,000
 - BUT two dipoles, 1 cm grid: ~16,000,000



DIPFIT: Dipole fitting 2. Nonlinear search

2. Fine fit step

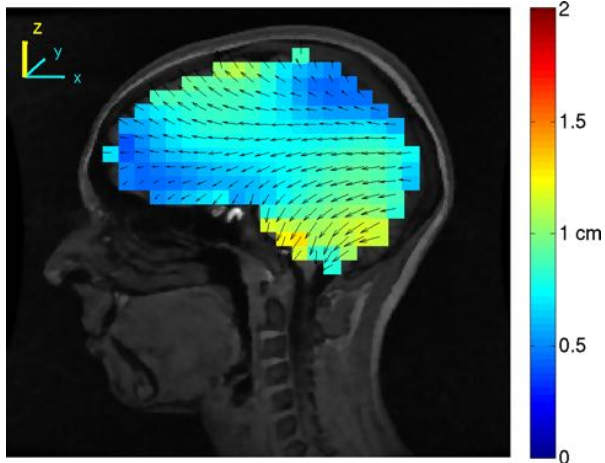
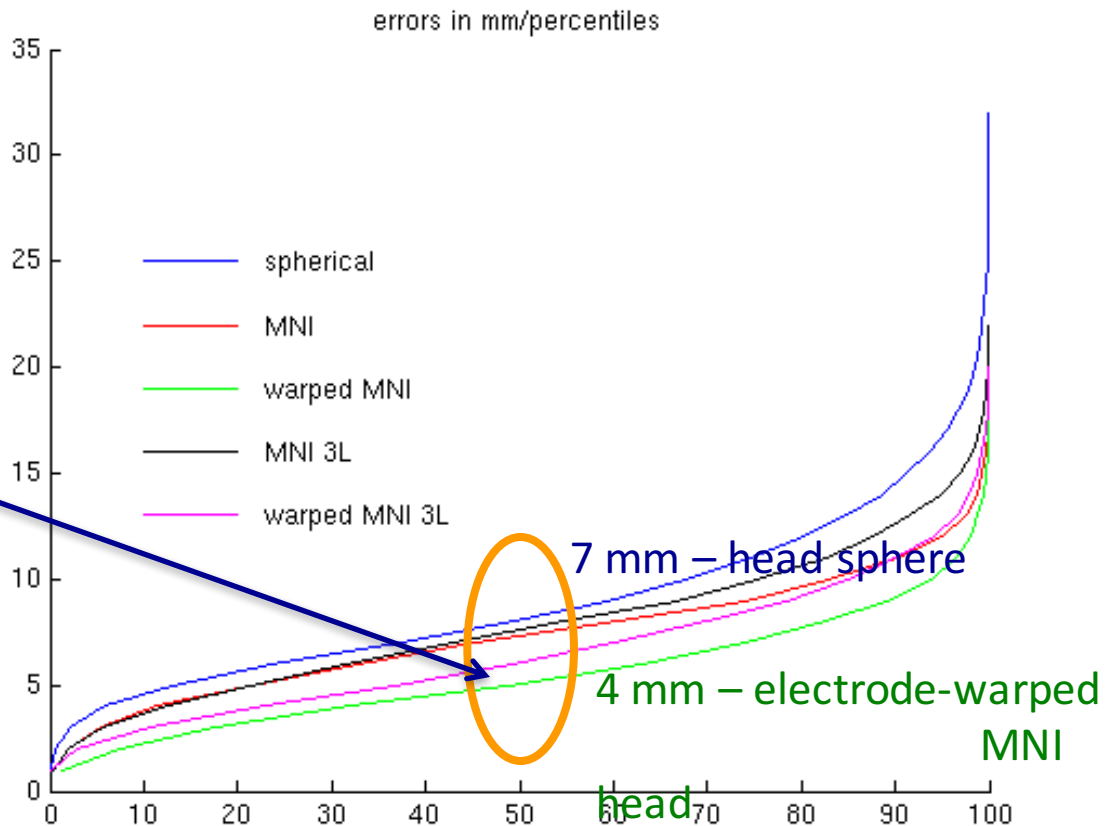
Start with the initial guess from coarse fitting

- Evaluate the local derivative of the goal (fit) function
- Then “walk down hill” to the most optimal solution

Number of iterative steps required = ~ 100

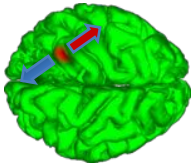
Effect of Template Head Model Choice On Estimated Dipole Locations

By Simulation: The median geometric error in dipole localization using the MNI template head model warped to measured electrode positions is only 4 mm.



BUT Additional dipole error contributors:

- Electrode co-registration error
- ICA numerical error (not enough data?)
- Source model geometry error
- Conductance value error (skull)

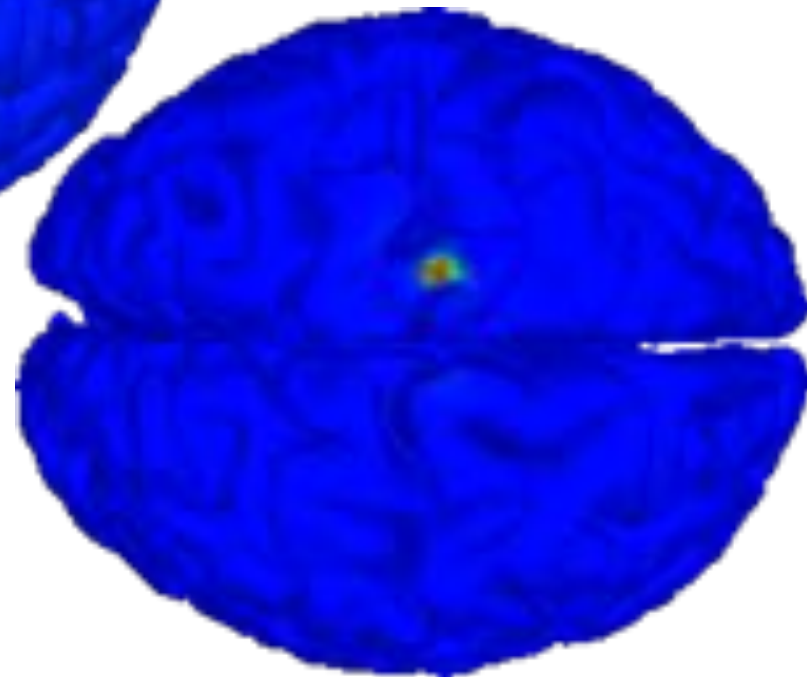
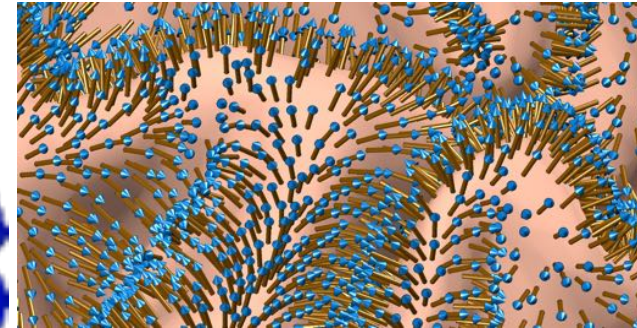
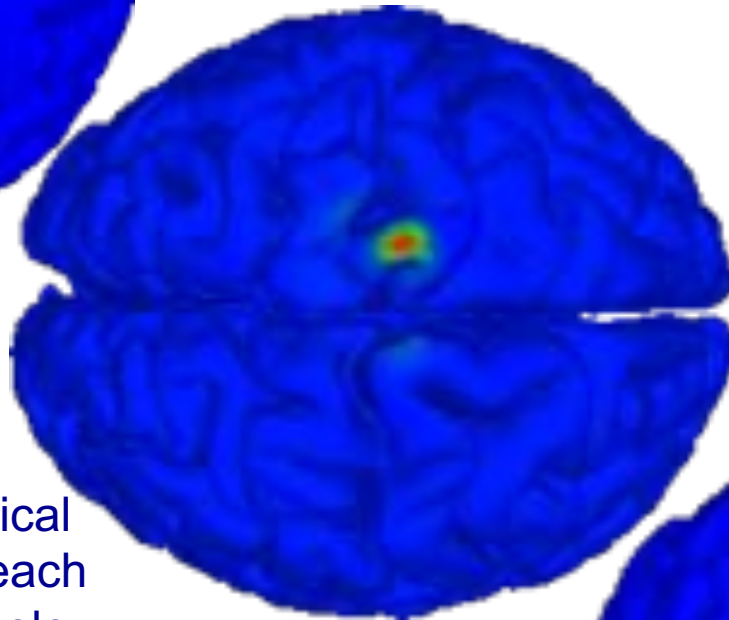
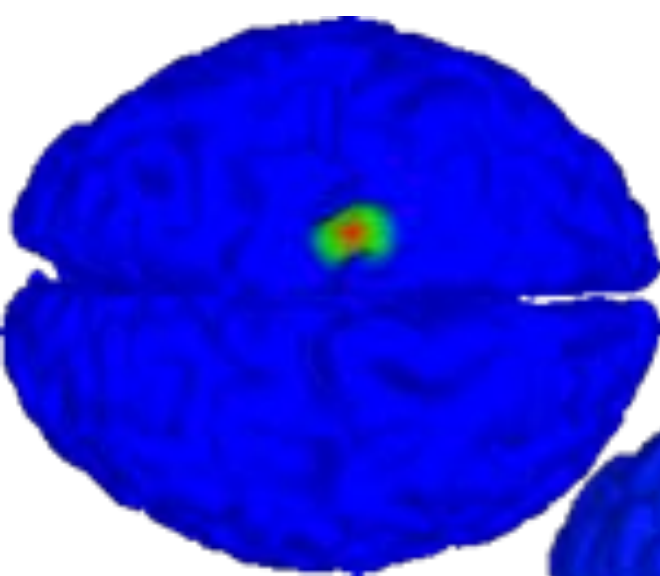


Distributed source models

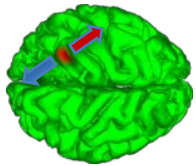
- The position of the source is not estimated as a whole
- Instead, On a pre-defined *source space* grid (3-D volume or cortical 2-D sheet)
 - Dipole strength is estimated *at each grid element*
 - In principle, a linear problem, easy to solve, BUT...
 - More “unknowns” (parameters) than “knowns” (channels, measurements), so ...
 - An infinite number of solutions can explain the data perfectly (not necessarily physiologically plausible!)
 - **Therefore**, additional source constraints are required ...

High-Resolution Distributed Source Localization

using a multiscale patch basis

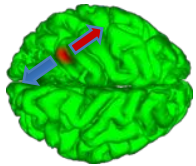


0. Build a high-res. cortical surface mesh; give each voxel an oriented dipole.
1. Compute a 'dictionary' of Gaussian patches conforming to the cortical surface centered at each cortical mesh voxel.
2. Use a 'sparsifying' approach to find the sum of the *fewest* of these patches that together produce the given source scalp or grid map.



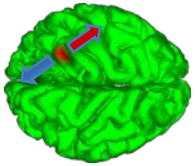
Summary

- An electromagnetic **forward head model** is required to interpret the sources of scalp maps
- Interpretation of scalp maps in terms of brain source distributions is “**inverse source estimation**”
- Mathematical techniques are available to aid in interpreting scalp maps as arising from particular brain sources
- These require an **inverse source model**, i.e. assumptions about the possible locations and nature of the sources (i.e., what attributes make them *physiologically plausible*).
- Then search for the *most plausible* source model.



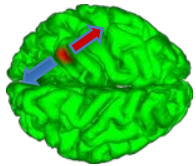
Summary

- **Inverse modeling**
 - Model assumption for volume conductor
 - Model assumption for source (i.e. dipole)
 - Additional assumptions on source
- **Single point-like sources**
- **Multiple point-like sources**
- **Distributed sources**
 - Different mathematical solutions
 - Dipole fitting (linear and nonlinear)
 - Linear estimation (regularized)



Summary

- **If we have MRI of the subject**
 - Subject specific head model
 - Distributed source localization
- **If we don't have the MRI**
 - Warped 4-layer MNI model (NFT)
 - Dipole source localization
- **Skull conductivity estimation** is as important as the head model used (SCALE)
- White matter modeling does not have a huge effect on source localization.



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